



**LaACES
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Errors and Uncertainty

Part 2



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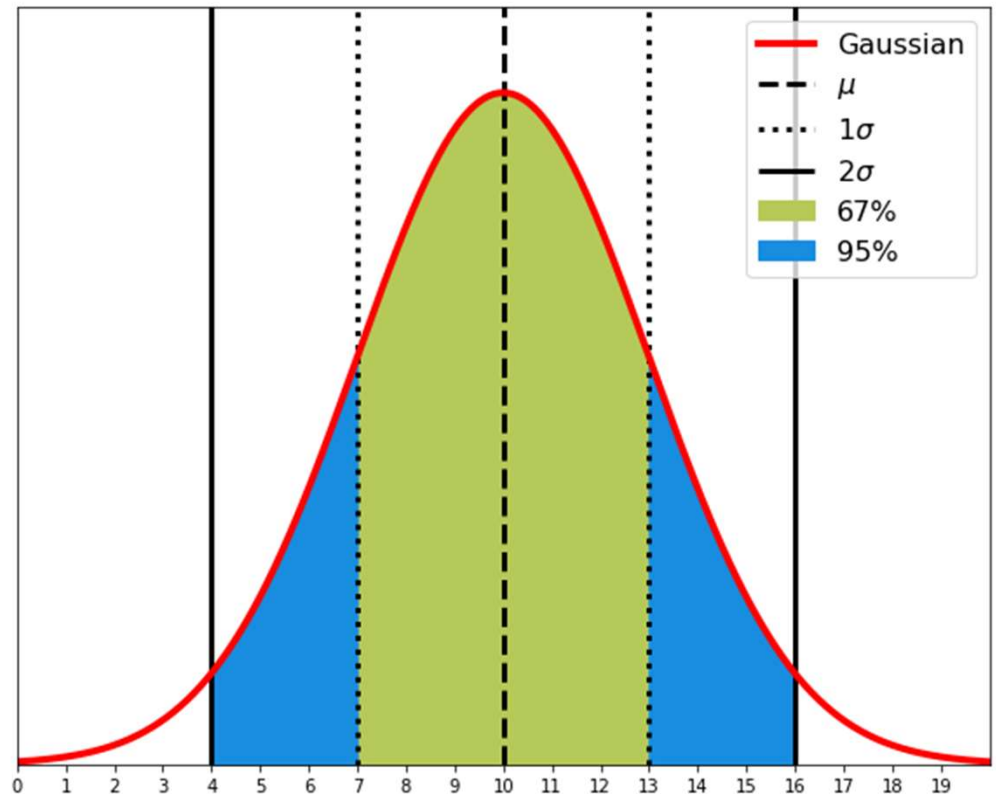
What is a Distribution

- Gives the relative chance(probability) getting a value when making 1 measurement of a particular quantity
 - As you make repeated measurements you are pulling more possible values out of the distribution
- You usually make a guess about the distribution for the measurement based on previous measurements, often assume the Normal Distribution
- When you make a single measurement you sampling the distribution, with multiple samples we can start to make more accurate statements about the distribution
- Shows how you should see the measurements to be distributed over all possible values if you were able to repeat the measurement and infinite amount of time
- Only addresses the random error, systematic error is assumed to be small or 0



Gaussian Distribution

- Most commonly used distribution
- Also called Normal Distribution
- $P(x) = k * e^{-\left(\frac{(x-\mu)^2}{2\sigma^2}\right)}$
- 3 constants (actually only 2) in equation
 - μ is the mean, the center and peak of the distribution and the most likely value
 - σ is the called variance which controls the width
 - The height is how to get that value when making a measurement
 - k is the normalization just scales the whole thing so that the sum (integral) is 1



A Gaussian distribution with $\mu=10$ and $\sigma=3$, the vertical lines show 1σ and 2σ from the mean. The green region contains about 67% of the total area and the combined green and blue contain 95% of the total area.



The Mean

- There are in fact 2 means we want to think about
- μ the mean of the distribution (Could be thought of as the true mean)
 - May be called expectation value
 - Simply the weighted average by probability of all possible values in the distribution
- \bar{X} the mean of the sample (i.e. the average value you measured)
 - $\bar{X} = \sum x_i / N$: where x_i are all the individual measurements and N is the number of measurements
 - This is what is called an estimator, we are trying to estimate some property of the distribution based on finite number of measurements, as N becomes large the estimator approaches the true value



Standard Deviations

- Standard Deviation by itself is a somewhat imprecise that could have different meanings in different contexts/fields
- Because of this you want to be specific which one you are using (define the equation somewhere)
- Not the same as the σ used
- 3 Standard Deviations with 3 Different meanings

- Population Standard Deviation

$$\sigma_p = \sqrt{\frac{\Sigma(x_i - \mu)^2}{N}}$$

- Sample Standard Deviation

$$\sigma_s = \sqrt{\frac{\Sigma(x_i - X)^2}{N - 1}}$$

- Standard Deviation of the Mean

$$\sigma_m = \sqrt{\frac{\sigma_s^2}{N}}$$



Standard Deviation (Population)

- $\sigma_p = \sqrt{\frac{\sum(x_i - \mu)^2}{N}}$
- Note that it depends on μ (the true mean) which for many applications you do not know
- However if your measurements are the entire set of values you are interested in (the entire population) you could use this
- You are trying to estimate the σ of the distribution
- What if we just replace μ with X (sample mean)
- Doing this underestimates the error so we do not want to use it
- As N becomes very large σ_p will equal σ



Standard Deviation (Sample)

- $\sigma_s = \sqrt{\frac{\sum(x_i - X)^2}{N-1}}$
- We can correct σ_p for the bias
- Because $N-1 < N$ σ_s will always be larger than σ_p
- As N becomes the -1 doesn't really matter so for a large enough N , $\sigma_p = \sigma_s$
- Used when you only have a sample of the population or distribution (almost always the case)
- With 1 measurement you get $\frac{0}{0}$, which is undefined, but that makes sense because you can not make any meaningful statement about a distribution based on 1 sample other than saying that sample is in the distribution
- However correcting the bias does not mean $\sigma = \sigma_p$ it just mean you are just as likely overestimate as underestimate σ
- As N becomes very large σ_s will equal σ



Standard Deviation of the Mean

- $\sigma_m = \sqrt{\frac{\sigma_s^2}{N}}$
- With σ_p, σ_s you are making estimating the error in a single measurement (estimating σ)
- σ_m you estimating how close to X (your sample mean) is to μ (the true mean of the distribution), the error in X
- Unlike σ_p, σ_s as N becomes very large σ_m will become zero



Example: Standard Deviation

- Suppose we make 5 measurements of the temperature with a digital thermometer that reads out to 0.1 Degrees
- First calculate the sum

B7		✕ ✓ <i>fx</i>		=SUM(B2:B6)	
	A	B	C	D	E
1		Value			
2		35.0			
3		35.0			
4		34.8			
5		34.5			
6		35.4			
7	Total	174.7			
8	N	5			
9	Mean	34.940000			



Example: Standard Deviation

- Suppose we make 5 measurements of the temperature with a digital thermometer that reads out to 0.1 Degrees
- First calculate the sum
- Next calculate the mean

	A	B	C	D
1		Value		
2		35.0		
3		35.0		
4		34.8		
5		34.5		
6		35.4		
7	Total	174.7		
8	N	5		
9	Mean	34.940000		

The screenshot shows an Excel spreadsheet with a formula bar at the top displaying '=B7/B8'. The spreadsheet contains a table with 9 rows and 5 columns. The first row is a header for the data values. The next five rows contain the individual temperature measurements. The final three rows (7, 8, and 9) contain the calculated total, number of measurements (N), and the mean, respectively.



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Example: Standard Deviation

- Then you need to subtract the mean from each measurement

	A	B	C	D	E
1		Value		Value - Mean	
2			35.0		0.0600
3			35.0		0.0600
4			34.8		-0.1400
5			34.5		-0.4400
6			35.4		0.4600
7	Total		174.7		
8	N		5		
9	Mean		34.9400		
10					



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Example: Standard Deviation

- Then you need to subtract the mean from each measurement
- Then square each of them

	A	B	C	D	E	F
1		Value		Value - Mean		Squared
2		35.0		0.0600		0.0036
3		35.0		0.0600		0.0036
4		34.8		-0.1400		0.0196
5		34.5		-0.4400		0.1936
6		35.4		0.4600		0.2116
7	Total	174.7				
8	N	5				
9	Mean	34.9400				



Example: Standard Deviation

- Then you need to subtract the mean from each measurement
- Then square each of them
- Sum the squares

	A	B	C	D	E	F
1		Value		Value - Mean		Squared
2			35.0		0.0600	0.0036
3			35.0		0.0600	0.0036
4			34.8		-0.1400	0.0196
5			34.5		-0.4400	0.1936
6			35.4		0.4600	0.2116
7	Total		174.7		Sum of the Squared	0.4320
8	N		5			
9	Mean		34.9400			
10						
11						
12						



Example: Standard Deviation

- Then you need to subtract the mean from each measurement
- Then square each of them
- Sum the squares
- Divide by N-1

	A	B	C	D	E	F
1		Value		Value - Mean		Squared
2		35.0		0.0600		0.0036
3		35.0		0.0600		0.0036
4		34.8		-0.1400		0.0196
5		34.5		-0.4400		0.1936
6		35.4		0.4600		0.2116
7	Total	174.7		Sum of the Squared		0.4320
8	N	5		Divide by N-1		0.1080
9	Mean	34.9400				
10						



Example: Standard Deviation

- Then you need to subtract the mean from each measurement
- Then square each of them
- Sum the squares
- Divide by N-1
- And take the square root

F9					
=SQRT(F8)					
	A	B	C	D	F
1		Value		Value - Mean	Squared
2		35.0		0.0600	0.0036
3		35.0		0.0600	0.0036
4		34.8		-0.1400	0.0196
5		34.5		-0.4400	0.1936
6		35.4		0.4600	0.2116
7	Total	174.7		Sum of the Squared	0.4320
8	N	5		Divide by N-1	0.1080
9	Mean	34.9400		Take the Square Root	0.328633535
10					
11					



Example: Standard Deviation

- However you could most programs have a built in standard deviation function
- But be careful to use the correct (sample not population)

The screenshot shows an Excel spreadsheet with a data table and a dropdown menu. The data table has columns A, B, and C. Column A contains labels, B contains values, and C contains calculations. A dropdown menu is open over cell C10, showing various standard deviation functions. The formula bar at the top shows '=stdev'.

	A	B	C	E	F	G
1		Value	Val			
2			35.0			
3			35.0			
4			34.8			
5			34.5			
6			35.4			
7	Total		174.7	Sum of the Squared		0.4320
8	N		5	Divide by N-1		0.1080
9	Mean		34.9400	Take the Square Root		0.328633535
10				or Just use formula		=stdev
11						

Dropdown menu options:

- STDEV.P
- STDEV.S
- STDEVA
- STDEVPA
- STDEV
- STDEVP
- DSTDEV
- DSTDEVP



Example: Standard Deviation

- However you could most programs have a built in standard deviation function
- But be careful to use the correct (sample not population)
- But can see gives the same result

	A	B	C	D	E	F
1		Value		Value - Mean		Squared
2		35.0		0.0600		0.0036
3		35.0		0.0600		0.0036
4		34.8		-0.1400		0.0196
5		34.5		-0.4400		0.1936
6		35.4		0.4600		0.2116
7	Total	174.7		Sum of the Squared		0.4320
8	N	5		Divide by N-1		0.1080
9	Mean	34.9400		Take the Square Root		0.328633535
10				or Just use formula		0.328633535



Example: Standard Deviation

- But what if we did the measurement with a bulb thermometer that could only has 0.5 deg resolution
- We get 0 for both the Standard Deviation and SD of the mean
- Does that mean no error?

	A	B	C	D	E	F	G
1		Value		Value - Mean		Squared	
2		35.0		0.0000		0.0000	
3		35.0		0.0000		0.0000	
4		35.0		0.0000		0.0000	
5		35.0		0.0000		0.0000	
6		35.0		0.0000		0.0000	
7	Total	175.0		Sum of the Squared		0.0000	
8	N	5		Divide by N-1		0.0000	
9	Mean	35.0000		Take the Square Root or Just use formula		0	
10						0	
11							
12				SD of Mean			0
13							
14							



What if my Standard Deviation is 0(or very small)?

- Let's say I measure the length of a metal bar with a ruler 10 times with a ruler marked in mm and I get 12 each time
- Calculating the σ_s you get 0 so I know the bar is exactly 12 mm, no uncertainty, down to the smallest fraction of a mm, right?
- NO! We have completely left out the other type of uncertainty, systematic
- Since the ruler is only marked in 1mm increments we would probably want to estimate the systematic error to be at least that large
 - Maybe you could argue 0.5mm but clearly if this was a digital measurement you couldn't go smaller than the last displayed digit
 - You would also want to include any accuracy given by the manufacturer specifications
- Need to estimate the systematic uncertainty and add it to the random uncertainty



Adding Errors

- Clearly the simplest solution would be to just add the errors together

$$\sigma = \sigma_1 + \sigma_2$$

- But we don't really expect them both to be at a max at the same time so can instead add them in quadrature

$$\sigma = \sqrt{(\sigma_1)^2 + (\sigma_2)^2}$$

- This assumes independent variables and normal distribution



Example: Adding Error

- Returning to our temperature example we can add the systematic and random errors

- $$\sigma = \sqrt{(\sigma_{rand})^2 + (\sigma_{sys})^2}$$

- For the bulb thermometer its easy, the random error we calculated was 0 so:

- $$\sigma = \sqrt{(0)^2 + 0.5^2} = 0.5^\circ\text{C}$$

- For a less trivial example lets look at the digital thermometer

- $$\begin{aligned}\sigma &= \sqrt{(0.1)^2 + (0.3286)^2} \\ &= 0.34347^\circ\text{C}\end{aligned}$$



Propagation of Error

- If f is a function of variables (x_1, x_2, \dots)

$$\sigma_f = \sqrt{\left(\frac{\partial f}{\partial x_1} \sigma_{x1}\right)^2 + \left(\frac{\partial f}{\partial x_2} \sigma_{x2}\right)^2 + \dots}$$

- This is a generalization of the addition formula
- Again assumes independent variables and normal distribution
- Partial Derivative treat all other variables as constants and take the derivative of that one variable (feel free to look up the derivatives)



Example Propagation of Error

- We want to know the volume of a rectangular object with dimensions of 10 mm x 12 mm x 5 mm
- The error for each measurement is dominated by systematic for each is 0.5mm
- $V = l * w * h$
- $V = 10mm * 12mm * 5mm = 600 mm^3$



Example Propagation of Error

- $V = l * w * h$
- V is a function of 3 variables l , w , and h

- $$\sigma_V = \sqrt{\left(\frac{\partial V}{\partial l} \sigma_l\right)^2 + \left(\frac{\partial V}{\partial w} \sigma_w\right)^2 + \left(\frac{\partial V}{\partial h} \sigma_h\right)^2}$$

- $$\frac{\partial V}{\partial l} = w * h \quad \frac{\partial V}{\partial w} = l * h \quad \frac{\partial V}{\partial h} = l * w$$

- $$\sigma_V = \sqrt{(wh\sigma_l)^2 + (lh\sigma_w)^2 + (lw\sigma_h)^2}$$



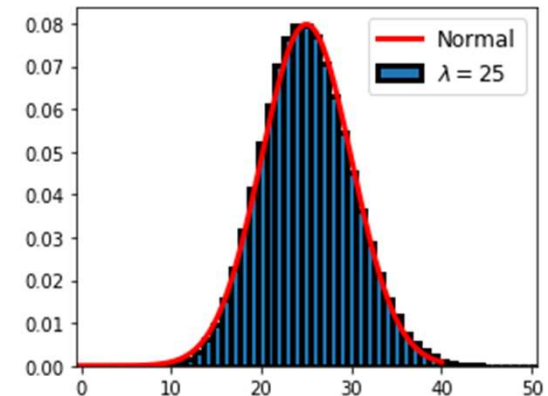
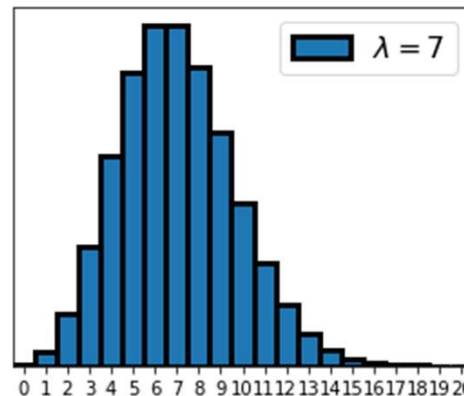
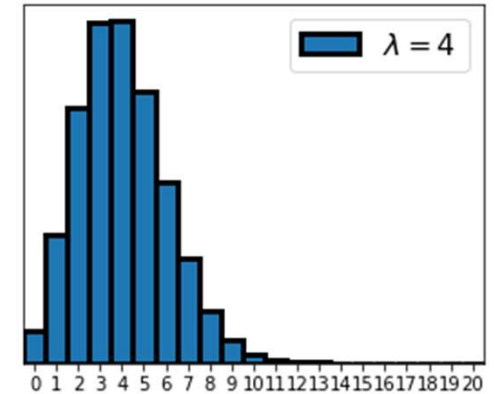
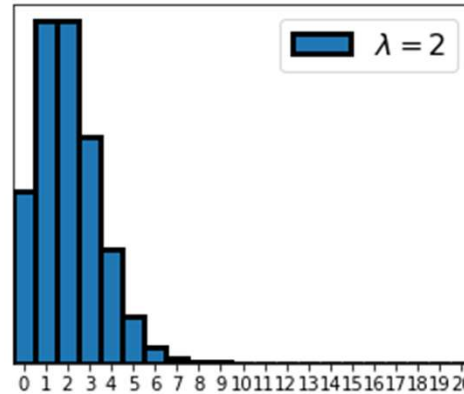
Example Propagation of Error

- $\sigma_V = \sqrt{(wh\sigma_l)^2 + (lh\sigma_w)^2 + (lw\sigma_h)^2}$
- Notice each term in parenthesis has units of volume
- $\sigma_l = \sigma_w = \sigma_h = 0.5 \text{ mm}$
- $\sigma_V = \sqrt{(12 * 5 * 0.5)^2 + (10 * 5 * 0.5)^2 + (10 * 12 * 0.5)^2}$
- $\sigma_V = 71.5 \text{ mm}^3$
- The volume is $600 \pm 70 \text{ mm}^3$
- More examples available in R05.02 Propagation of Error
- https://laspace.lsu.edu/laaces/wp-content/uploads/2020/08/R05.02_Propagation_of_Errors.pdf



Poisson Distribution

- Used for many types of counting measurements like radioactive decay, photon counting, river flooding..
- k is number of occurrences, λ is the average number of occurrences
- $P(k) = \frac{\lambda^k e^{-\lambda}}{k!}$ (Probability of having 0 floods, 1 flood, k floods in the next 100 years, when on average have λ every 100 years)
- When λ is very large just becomes a normal distribution



Poisson distributions of various λ



But why Gaussian?

- If there are other distributions, why do we usually assume a Gaussian Distributions
- In the large number case (big n or λ) other distributions become close to a Gaussian
- There is good math for doing propagation and error handling
- It is a good model for many physical measurements
 - Can prove this is the case from a very many very small errors adding up from the Central Limit Theorem



Reporting Measurements

- If I think the error in a measurement is 0.5 mm does it make sense to report the average as 12.003mm
- The common practice is to round the error to 1 or 2 significant digit and then round the corresponding measurement to that digit
 - So we would report the values as $12.0 \pm 0.5 \text{mm}$
- However do not round intermediate values used for calculations because you do not want to have rounding errors compound
- Also errors should have the same units as the measurement
- You want to be clear about how you have calculated errors and what you mean with your \pm , show your work



Putting it all together

- Let's assume, we first did repeated temperature measurements at one temperature to show the random error is small compared to the 0.5 error from our bulb thermometer
- From the pixel size and signal width in Spectrogram software we estimate the systematic uncertainty of to be 11 Hz
- We decide we need to take 5 independent frequency measurements at each temperature

	Temp (C)	95.0	Error in T	0.5
	Frequencies (Hz)			
Beep #	1	2		
1	3767	5038	1271	
2	3724	4995	1271	
3	3746	4995	1249	
4	3746	5016	1270	
5	3767	4995	1228	
		Mean	1257.8	
		Std Dev	19.12328	
		SD Mean	8.552193	
		Syst Err	11	
		Total Freq		
		Error	13.93341	



Putting it all together

- We will calculate the mean of our 5 frequencies and use that as our fitting point
- We then need to calculate the standard deviation of that mean to determine the random frequency error for that mean value
- The we need to add the systematic frequency error to the random to find the total frequency error
- Doing this gives us our first datapoint (1257.8±14 Hz, 95.0 ±0.5°C)

	Temp (C)	95.0	Error in T	0.5
	Frequencies (Hz)			
Beep #	1	2		
1	3767	5038	1271	
2	3724	4995	1271	
3	3746	4995	1249	
4	3746	5016	1270	
5	3767	4995	1228	
		Mean	1257.8	
		Std Dev	19.12328	
		SD Mean	8.552193	
		Syst Err	11	
		Total Freq		
		Error	13.93341	



Calculating all our data points

- Now repeat the process for all temperature and frequency measurements
- This gives us a set of x (frequency) and y (temperature) points with a horizontal and vertical error for each datapoint

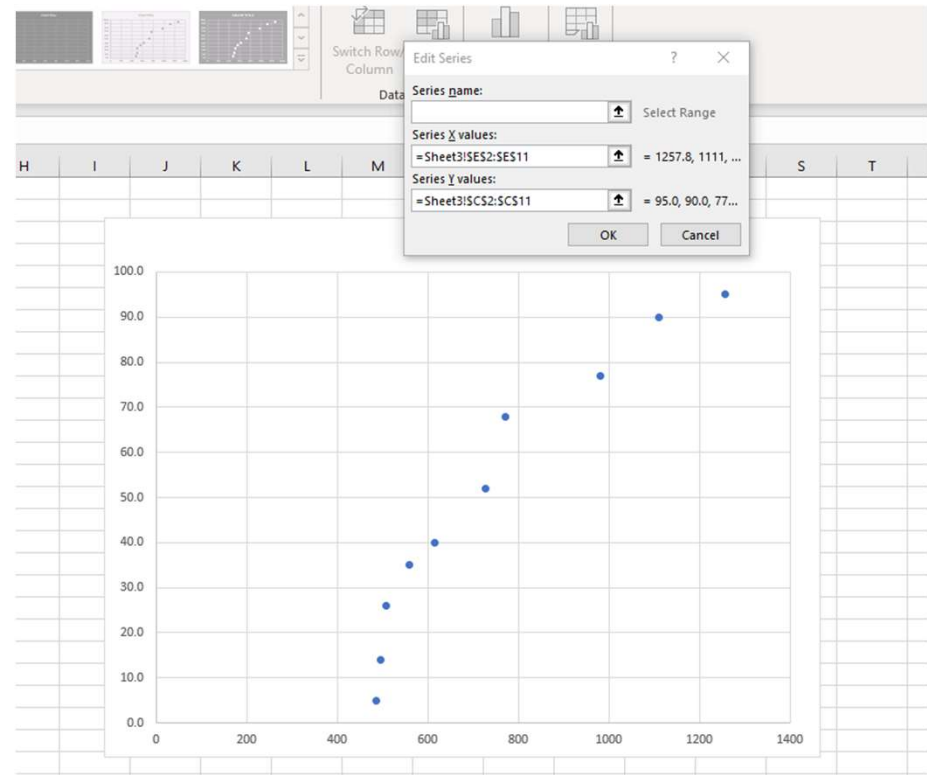
	C	D	E	F	G
1	Temperature (C)	Error T	Frequency (Hz)	Error f	
2		95.0	0.5	1257.8	13.93341
3		90.0	0.5	1111	16.90266
4		77.0	0.5	981.8	15.44798
5		68.0	0.5	771.6	11.84736
6		52.0	0.5	728	11.7047
7		40.0	0.5	616	12.21475
8		35.0	0.5	560	13.01538
9		26.0	0.5	508.4	12.19672
10		14.0	0.5	495	11
11		5.0	0.5	487.2	12.24908
12					



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Plot the points

- Now we want to plot all of the points together
- Since the goal of the experiment is to be able to read a frequency and be able to tell what temperature the thermistor is, we want T as a function f
- So we pick f as the x values and T as the y values

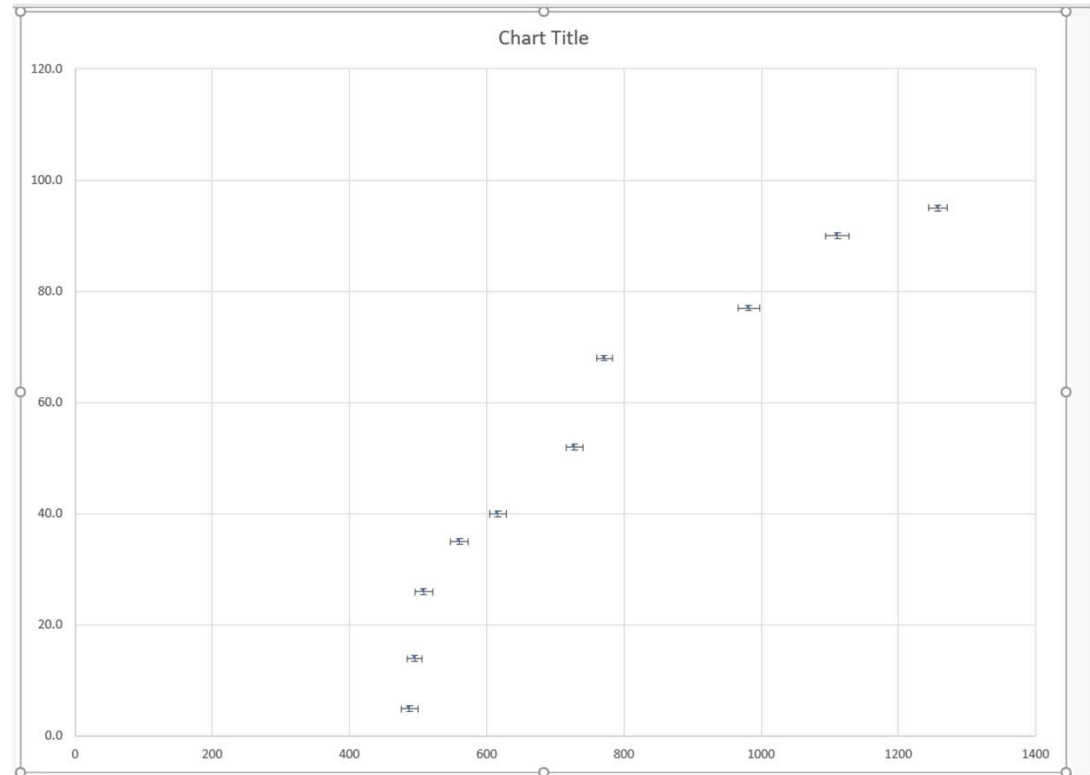




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Add Error Bars

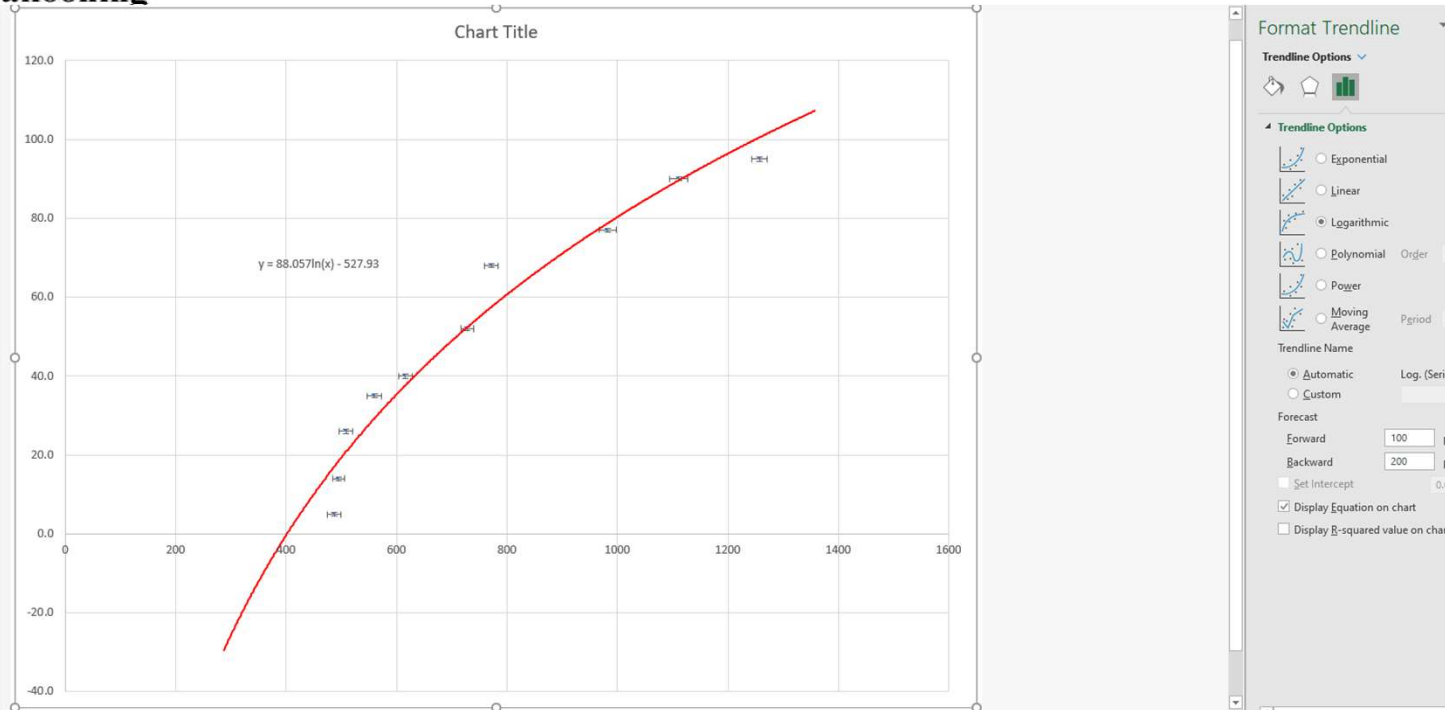
- We add the error bars to our plot
- Select in this case our error is symmetric, so we use the same value for both the positive and negative error
- Additionally we want to select the option that lets us specify values for error and not a percentage, standard deviation, or fixed value for example
- Add both horizontal and vertical error bars, using the errors we calculated
- It may be necessary to adjust to point marker size or add a caption if the errors are small





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Add a trendline



- Finally we want to add a trendline
- Clearly the data is not linear
- Ideally, we would have some theoretical basis for picking a particular fit but we can also try seeing what matches the data
- Also probably want to show the equation of the fit on our plot



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Finish the Plot and Draw Conclusions

- Don't forget to add the axes titles, units, plot title, etc.
- If we have a good fit and correctly assessed our errors, we expect $\sim 2/3$ of our points error bars to overlap with our fit line (Remember 67% 1σ)
- Many less than $2/3$
 - Maybe not a good fit function
 - Possibly underestimated errors, missed systematics
- Many more than $2/3$
 - Too many constants in your function
 - Overestimated error, manufacturer specification often give “guaranteed to be this accurate” rather than a more scientific error