HASP 2015

<u>University of North Dakota- University of north Florida (UND-UNF) Payload</u> <u>Preliminary Payload Specification and Integration Plan (PSIP)</u>

Payload Title:

Measurements of ozone profile in the stratosphere and pollutant gases in atmosphere and troposphere using improved nanocrystalline sensors payload on a high altitude balloon platform.

Payload Class: Small Payload

Payload ID: 7

Institution: University of North Dakota and University of North Florida (UND-UNF)

Contact Name:

UNF – Brittany Nassau (Students Team Leader), Dr. Nirmal Patel

UND - Dr. Ronald Fevig

Contact Phone: Brittany: 904-495-1765

Dr. Nirmal Patel (904) 200-2855, Dr. Ron Fevig (520) 820-3440,

Contact E-mail: Brittany.Nassau@gmail.com

npatel@unf.edu, rfevig@aero.und.edu,

Submit Date: April 20, 2015

Mechanical Specifications: The measured weight budget of various parts of the payload is given in the table-1.

Table-1 Payload weight and dimension budget

Item:	Dimension	Mass (kg)
8 Ozone sensors box #1 (including fan, heater, box)	3 x 2 x 1 inch	0.200
8 Ozone sensors box #2 (including fan, heater, box)	3 x 2 x 1 inch	0.200
8 Reducing gas sensors box #3(including fan, heater, box)	3 x 2 x 1 inch	0.200
Microcontroller PCB with mounted components	4 x 6 inch	0.300
Payload body, top plate and thermal blanket	9 x 6 x 6 inch	1.050
Few Cables, 1 GPS, 2 LEDs, 3 Photodiodes, nuts and		0.250
bolts		
HASP mounting plate	7.9 x 7.9 inch	0.550
Total mass ± Uncertainties		2.750.0±0.055 kg

A. Provide a mechanical drawing detailing the major components of your payload and specifically how your payload is attached to the payload mounting plate

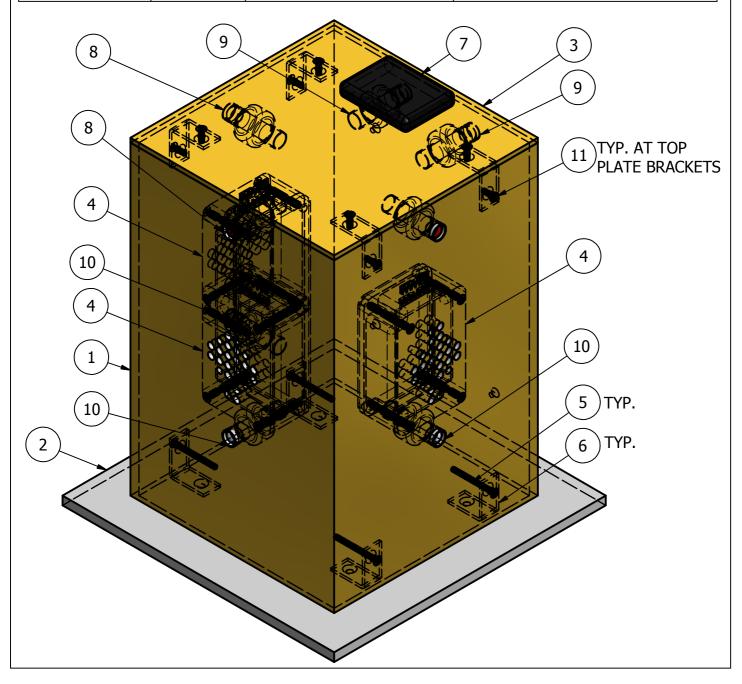
The 2015 payload body is similar to the previous HASP2014 payload body, but reduces in the height. The important features of our newly designed payload body are easy to open and close the payload, easy access of PCB and sensor boxes, low rate of outgassing under low pressure, better stability with thermal and impact, and also reusable. The payload metal parts were procured payload from the supplier www.onlinemetals.com and are listed in the table-2.

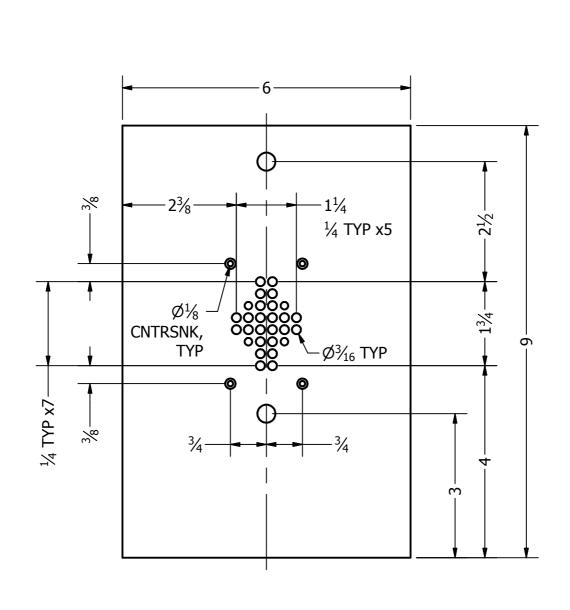
Table-2 Payload metal parts

Name	Size	Purpose
Aluminum Extruded Square Tube Part #6063-T52	height 9" w x d: 6" x 6" wall thickness: 0.125"	Payload body
Aluminum Sheet Part#3003-H14	6" x 6" Thickness:1/8"	Top lid

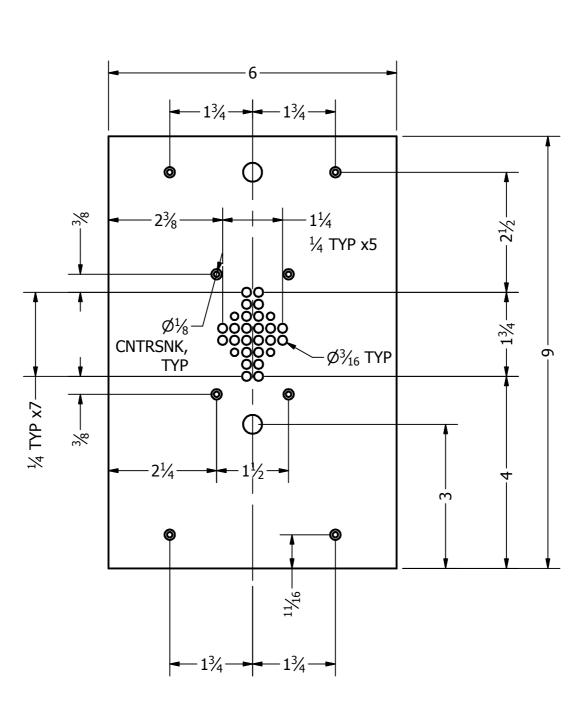
Joe made design drawing based on the previous payload. Mathew and Bernado are learning CNC Machining System in the workshop of Department of Engineering of UNF. Ken is helping them. The revised design diagrams are shown in Fig. 1 (a) to (i).

PARTS LIST			
ITEM	QTY	PART NUMBER	DESCRIPTION
1	1	Body	6x6x1/8" POLYETHLENE TUBE
2	1	Mount	AS PROVIDED
3	1	Тор	1/8" POLYETHLENE PLATE
4	3	PCB	MACHINED ALUMINUM, SEE DETAIL
5	16	Screw	3/16" x 2"
6	8	Bracket	1"X1" L BRACKET
7	1	GPS	GPS
8	3	LEDred	LED LIGHT, RED
9	2	LEDgreen	LED LIGHT, GREEN
10	3	LEDwhite	LED LIGHT, WHITE
11	8	ScrewShort	3/16" x3/8"



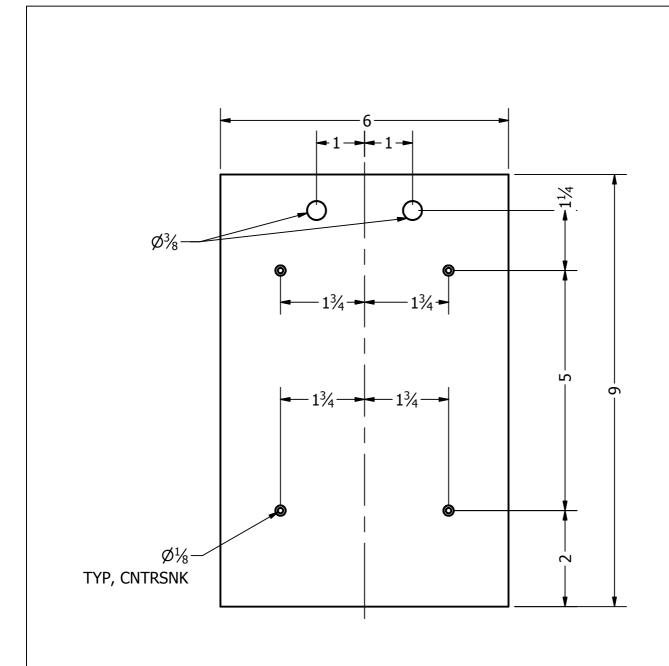


SIDE 1 SCALE 1:2

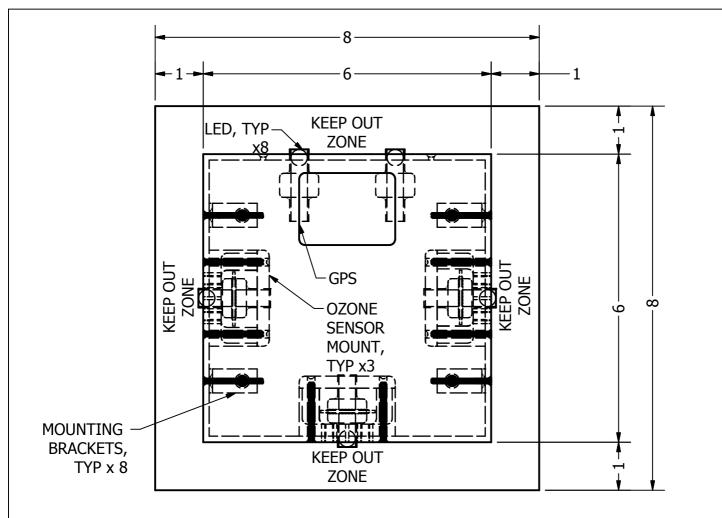


SIDE 2 (SIDE 4 SIMILAR)

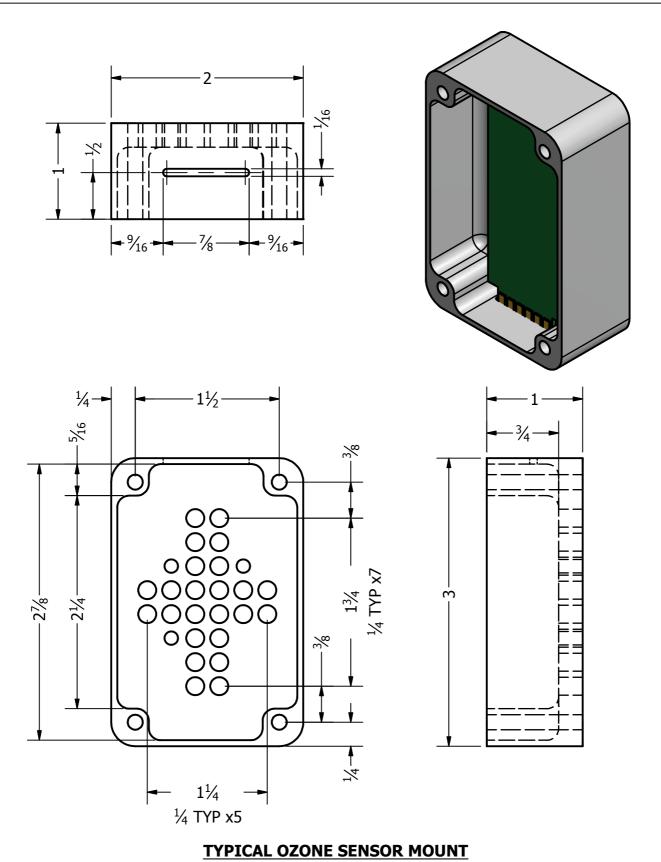
SCALE 1:2



SIDE 3 SCALE 1:2



TOP VIEW SCALE 1:2



(3 REQUIRED) SCALE 1:1

Fig.2 (a) shows the 8 sensors array mounted on the printed circuit board (PCB). These sensors (US Patent Pending) will be fabricated, tested and calibrated by the student's team of UNF in the Dr. Patel's sensors laboratory. The sensor PCB is mounted in the metal box (Fig. 2b) along with one heater, fan and temperature sensor.

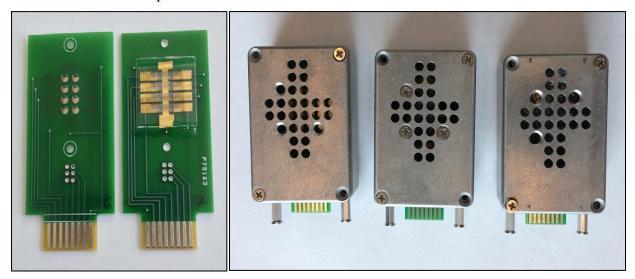


Fig. 2 (a) Sensors mounted on PCB and (b) Sensors boxes

The sensor box will be mounted on each side of the payload. The purpose of each sensor box is listed in the table-3.

Table-3 Purpose of sensors

Sensors	Sensor Materials	Purpose
Box#		
1	Nanocrystalline Indium tin Oxide (ITO) thin film	To detect ozone gas in the stratosphere
2	Nanocomposite of Zinc Oxide (ZnO) and Indium tin Oxide (ITO) thin film	To detect ozone gas in the stratosphere
3	Nanocomposite of WO ₃ +SnO ₂ thin film	To detect pollutant gases in the troposphere

A. If you are flying anything that is potentially hazardous to HASP or the ground crew before or after launch, please supply all documentation provided with the hazardous components (i.e. pressurized containers, radioactive material, projectiles, rockets...)

Not Applicable

Other relevant mechanical information

(i) The payload will be mounted on the HASP mounting plate by 4 L-brackets, bolts, washers and nuts.

(ii) Thermal blanket made of aluminized heat barrier having adhesive backed (Part No. 1828-12x24) (Make: www.PegasusAutoRacing.com) will be applied on the outer surface of the payload for the improvement of thermal stability. The high reflective surface of the material is capable of withstanding radiant temperatures in excess of 1000°C.

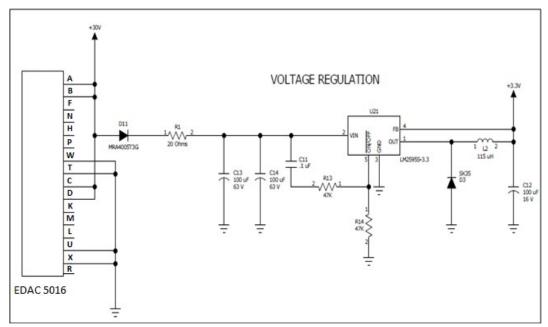
II. Power Specifications:

A. Measured current draw at 30 VDC for different function of circuit operation is listed in the table-4.

Table-4 Current Draw

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Circuit Function	Current draw (mA)	
Payload Power ON, but all heaters OFF	30±5	
Payload Power ON and Heater #1 ON	140±5	
Payload Power ON, Heater #1 and 2 ON	250±5	
Payload Power ON, Heater #1, 2 and 3 ON	350±5	

B. If HASP is providing power to your payload, provide a power system wiring diagram starting from pins on the student payload interface plate EDAC 516 connector through your power conversion to the voltages required by your subsystems.



C. Other relevant power information

None

III. Downlink Telemetry Specifications:

A. Serial data downlink format:

Packetized- Record +/- 232 bytes transmitting in 5 second intervals

B. Approximate serial downlink rate

372 bps

C. Specify your serial data record including record length and information contained in each record byte.

11 bytes for data packet synchronization

6 bytes GPS source indicator

10 bytes for UTC time

7 bytes for MLS altitude

24x6 bytes for filtered ozone data

3x6 bytes for local sensor temperature

3x6 bytes for photo-cell

6 bytes CPU temp

6 bytes MCU power rail voltage

6 bytes MCU power rail current

6 bytes for atmospheric pressure in mbar

6 bytes for heater status

D. Number of analog channels being used:

0

E. If analog channels are being used, what are they being used for?

Not Applicable

F. Number of discrete lines being used:

0

G. If discrete lines are being used what are they being used for?

Not Applicable

Are there any on-board transmitters? If so, list the frequencies being used and the transmitted power.

NO

H. Other relevant downlink telemetry information.

Not Applicable

IV. Uplink Commanding Specifications:

A. Command uplink capability required:

Yes

B. If so, will commands be uplinked in regular intervals:

No

- C. How many commands do you expect to uplink during the flight (can be an absolute number or a rate, i.e. *n commands per hour*)
 - 1-2 commands per hour maximum
- D. Provide a table of all of the commands that you will be up linking to your payload

Table 5: Uplink Commands

#	Command Description	Cmd. Code	Checksum	Confirmation/Notes
1	Reset	0x71	0x31	"HELLO" upon reset
2	Erase data in flash	0x72	0x32	"ERASING FLASH""COMPLETE"
3	Upload data in flash	0x73	0x33	"NO DATA"
4	n/a	n/a	n/a	n/a
5	Master Heater Override Switch On	0x75	0x35	Heater Status (default)
6	Master Heater Override Switch Off	0x76	0x36	Heater Status
7	On Board Data Logging On	0x77	0x37	Data (default)
8	On Board Data Logging Paused	0x78	0x38	Data empty
9	Stream UBLOX data	0x79	0x39	"HASP UBLOX"
10	Stream HASP GPS data	0x7A	0x3A	"HASP "

E. Are there any on-board receivers? If so, list the frequencies being used.

NO

F. Other relevant uplink commanding information.

None

G. <u>Request</u>: UND-UNF Team is requesting the HASP to provide us the GPS strings from the HASP gondola every 1 second.

V. Integration and Logistics

A. Date and Time of your arrival for integration:

7/27/2014 Time: TBD

- B. Approximate amount of time required for integration:
 - 3 4 Hours
- C. Name of the integration team leader:

Brittany Nassau (UNF)

D. Email address of the integration team leader:

Brittany.Nassau@gmail.com

E. List **ALL** integration participants (first and last names) who will be present for integration with their email addresses:

Brittany Nassau (UNF) - <u>Brittany.Nassau@gmail.com</u>
Joseph Thomas Silas (UNF) - <u>cruiser_9482@yahoo.com</u>
Matthew Linekin (UNF) - <u>n00601480@ospreys.unf.edu</u>
Bernardo Ladeira Craveiro (UNF) - <u>n00868896@ospreys.unf.edu</u>
Dr. Nirmal Patel (UNF) - <u>npatel@unf.edu</u>
Sean McCloat (UND) may present for integration.

F. Define a successful integration of your payload:

Payload successfully mounts to platform, both mechanically and electronically. Payload successfully performs a sensor/communication check, and systems health checks to ensure proper data/headers formatting. After an initial test sequences a steady 1 Hz flashing STATUS LED indicates a sound system. After initial system testing is complete the system will successfully packet and send data to HASP computer and ground station computer will decipher and provides data plots of ozone concentration in real-time during the final preflight testing (the thermal vacuum testing).

- G. List all expected integration steps:
 - 1. Successfully interface the payload to platform.
 - a. Mount the payload to the HASP platform
 - b. Connect and interface the payload with the power system and the communication bus
- H. List all checks that will determine a successful integration:
 - a) Perform communication and data checks.
 - b) Successfully execute command set.
 - c) Monitor system to ensure proper operation via real time data stream of all sensors data readings, pressure, photo voltage of light sensors and ambient temperature.
- I. List any additional LSU personnel support needed for a successful integration other than directly related to the HASP integration (i.e. lifting, moving equipment, hotel information/arrangements, any special delivery needs...):
 - No. Thank you very much. But, your blessings are always solicited.
- J. List any LSU supplied equipment that may be needed for a successful integration:

Team will carry all required equipment and tools. We may need soldering station, oscilloscope and heat gun.